## Discrete-Time Markov Chains

Topics

- State-transition matrix
- Network diagrams
- Examples: gambler's ruin, brand switching, IRS, craps
- Transient probabilities
- Steady-state probabilities


## Discrete - Time Markov Chains

Many real-world systems contain uncertainty and evolve over time.

Stochastic processes (and Markov chains) are probability models for such systems.

A discrete-time stochastic process is a sequence of random variables $X_{0}, X_{1}, X_{2}, \ldots$ typically denoted by $\left\{X_{n}\right\}$.

Origins: Galton-Watson process $\rightarrow$ When and with what probability will a family name become extinct?

## Components of Stochastic Processes

The state space of a stochastic process is the set of all values that the $X_{n}$ 's can take.
(we will be concerned with stochastic processes with a finite \# of states )

Time: $n=0,1,2, \ldots$
State: $v$-dimensional vector, $\mathbf{s}=\left(s_{1}, s_{2}, \ldots, s_{v}\right)$
In general, there are $m$ states,

$$
\mathbf{s}^{1}, \mathbf{s}^{2}, \ldots, \mathbf{s}^{m} \text { or } \mathbf{s}^{0}, \mathbf{s}^{1}, \ldots, \mathbf{s}^{m-1}
$$

Also, $X_{n}$ takes one of $m$ values, so $X_{n} \leftrightarrow \mathbf{s}$.

## Gambler's Ruin

At time 0 I have $X_{0}=\$ 2$, and each day I make a $\$ 1$ bet. I win with probability $p$ and lose with probability $1-p$. I'll quit if I ever obtain $\$ 4$ or if I lose all my money.

State space is $\mathbf{S}=\{0,1,2,3,4\}$
Let $X_{n}=$ amount of money I have after the bet on day $n$.

$$
\begin{aligned}
& \text { So, } X_{1}=\left\{\begin{array}{l}
3 \text { with probabilty } p \\
1 \text { with probabilty } 1-p
\end{array}\right. \\
& \text { If } X_{n}=4 \text {, then } X_{n+1}=X_{n+2}=\cdots=4 . \\
& \text { If } X_{n}=0 \text {, then } X_{n+1}=X_{n+2}=\cdots=0 .
\end{aligned}
$$

## Markov Chain Definition

A stochastic process $\left\{X_{n}\right\}$ is called a Markov chain if $\operatorname{Pr}\left\{X_{n+1}=j \mid X_{0}=k_{0}, \ldots, X_{n-1}=k_{n-1}, X_{n}=i\right\}$
$=\operatorname{Pr}\left\{X_{n+1}=j \mid X_{n}=i\right\} \quad \leftarrow$ transition probabilities
for every $i, j, k_{0}, \ldots, k_{n-1}$ and for every $n$.
Discrete time means $n \in N=\{0,1,2, \ldots\}$.
The future behavior of the system depends only on the current state $i$ and not on any of the previous states.

## Stationary Transition Probabilities

$\operatorname{Pr}\left\{X_{n+1}=j \mid X_{n}=i\right\}=\operatorname{Pr}\left\{X_{1}=j \mid X_{0}=i\right\}$ for all $n$ (They don't change over time)
We will only consider stationary Markov chains.
The one-step transition matrix for a Markov chain with states $\mathbf{S}=\{0,1,2\}$ is

$$
\mathbf{P}=\left[\begin{array}{lll}
p_{00} & p_{01} & p_{02} \\
p_{10} & p_{11} & p_{12} \\
p_{20} & p_{21} & p_{22}
\end{array}\right]
$$

where $p_{i j}=\operatorname{Pr}\left\{X_{1}=j \mid X_{0}=i\right\}$

## Properties of Transition Matrix

If the state space $\mathbf{S}=\{0,1, \ldots, m-1\}$ then we have

$$
\sum_{j} p_{i j}=1 \quad \forall i \quad \text { and } \quad p_{i j} \geq 0 \quad \forall i, j
$$

(we must go somewhere)
(each transition has probability $\geq 0$ )

Gambler's Ruin Example

|  | 0 | 1 | 2 | 3 | 4 |
| :--- | :--- | :--- | :--- | :--- | :--- |
| 0 | 1 | 0 | 0 | 0 | 0 |
| 1 | $1-p$ | 0 | $p$ | 0 | 0 |
| 2 | 0 | $1-p$ | 0 | $p$ | 0 |
| 3 | 0 | 0 | $1-p$ | 0 | $p$ |
| 4 | 0 | 0 | 0 | 0 | 1 |

## Computer Repair Example

- Two aging computers are used for word processing.
- When both are working in morning, there is a $30 \%$ chance that one will fail by the evening and a $10 \%$ chance that both will fail.
- If only one computer is working at the beginning of the day, there is a $20 \%$ chance that it will fail by the close of business.
- If neither is working in the morning, the office sends all work to a typing service.
- Computers that fail during the day are picked up the following morning, repaired, and then returned the next morning.
- The system is observed after the repaired computers have been returned and before any new failures occur.


## States for Computer Repair Example

| Index | State | State definitions |
| :---: | :---: | :--- |
| 0 | $\mathbf{s}=(0)$ | No computers have failed. The <br> office starts the day with both <br> computers functioning properly. |
| 1 | $\mathbf{s}=(1)$ | One computer has failed. The <br> office starts the day with one <br> working computer and the other in <br> the shop until the next morning. |
| 2 | $\mathbf{s}=(2)$ | Both computers have failed. All <br> work must be sent out for the day. |

## Events and Probabilities for Computer Repair Example

| Index | Current <br> state | Events | Prob- <br> ability | Next state |
| :---: | :---: | :--- | :---: | :---: |
| 0 | $s^{0}=(0)$ | Neither computer fails. | 0.6 | $s^{\prime}=(0)$ |
|  | One computer fails. | 0.3 | $s^{\prime}=(1)$ |  |
| 1 | $s^{1}=(1)$ | Both computers fail. <br> Remaining computer does <br> neturned. <br> rethe other is | 0.8 | $s^{\prime}=(2)$ |
|  |  | Remaining computer fails <br> and the other is returned. | 0.2 | $s^{\prime}=(0)$ |
| 2 | $s^{2}=(2)$ | Both computers are <br> returned. | 1.0 | $s^{\prime}=(0)$ |

## State-Transition Matrix and Network

The events associated with a Markov chain can be described by the $m \times m$ matrix: $\mathbf{P}=\left(p_{i j}\right)$.
For computer repair example, we have:
$\mathbf{P}=\left[\begin{array}{ccc}0.6 & 0.3 & 0.1 \\ 0.8 & 0.2 & 0 \\ 1 & 0 & 0\end{array}\right]$

State-Transition Network

- Node for each state
- Arc from node $i$ to node $j$ if $p_{i j}>0$.

For computer repair example:


## Procedure for Setting Up a DTMC

1. Specify the times when the system is to be observed.
2. Define the state vector $\mathbf{s}=\left(s_{1}, s_{2}, \ldots, s_{v}\right)$ and list all the states. Number the states.
3. For each state sat time $n$ identify all possible next states s' that may occur when the system is observed at time $n+1$.
4. Determine the state-transition matrix $\mathbf{P}=\left(p_{i j}\right)$.
5. Draw the state-transition diagram.

## Repair Operation Takes Two Days

One repairman, two days to fix computer.
$\rightarrow$ new state definition required: $\mathbf{s}=\left(s_{1}, s_{2}\right)$
$s_{1}=$ day of repair of the first machine
$s_{2}=$ status of the second machine (working or needing repair)
For $s_{1}$, assign 0 if $1^{\text {st }}$ machine has not failed
1 if today is the first day of repair
2 if today is the second day of repair
For $s_{2}$, assign 0 if $2^{\text {nd }}$ machine has not failed
1 if it has failed

## State Definitions for 2-Day Repair Times

| Index | State | State definitions |
| :---: | :---: | :--- |
| 0 | $s^{0}=(0,0)$ | No machines have failed. |
| 1 | $s^{1}=(1,0)$ | One machine has failed and today is in <br> the first day of repair. |
| 2 | $s^{2}=(2,0)$ | One machine has failed and today is in <br> the second day of repair. |
| 3 | $s^{3}=(1,1)$ | Both machines have failed; today one is <br> in the first day of repair and the other is <br> waiting. |
| 4 | $s^{4}=(2,1)$ | Both machines have failed; today one is <br> in the second day of repair and the <br> other is waiting. |

## State-Transition Matrix for 2-Day Repair Times

\(\mathbf{P}=\left[\begin{array}{ccccc}0 \& 1 \& 2 \& 3 \& 4 <br>
0.6 \& 0.3 \& 0 \& 0.1 \& 0 <br>
0 \& 0 \& 0.8 \& 0 \& 0.2 <br>
0.8 \& 0.2 \& 0 \& 0 \& 0 <br>
0 \& 0 \& 0 \& 0 \& 1 <br>

0 \& 1 \& 0 \& 0 \& 0\end{array}\right]\)| 0 |
| :---: |
| 1 |
| 2 |
| 3 |
| 4 |

For example, $p_{14}=0.2$ is probability of going from state 1 to state 4 in one day, where $s^{1}=(1,0)$ and $s^{4}=(2,1)$

## Brand Switching Example

Number of consumers switching from brand $i$ in week 26 to brand $j$ in week 27

| Brand | $(j) 1$ | 2 | 3 | Total |
| :---: | :---: | :---: | :---: | :---: |
| $(i)$ |  |  |  |  |
| 1 | 90 | 7 | 3 | 100 |
| 2 | 5 | 205 | 40 | 250 |
| 3 | 30 | 18 | 102 | 150 |
| Total | 125 | 230 | 145 | 500 |

This is called a contingency table.
$\rightarrow$ Used to construct transition probabilities.

## Empirical Transition Probabilities

 for Brand Switching, $p_{i j}$| Brand | $(j) 1$ | 2 | 3 |
| :---: | :---: | :---: | :---: |
| $(i)$ | $\frac{90}{100}=0.90$ | $\frac{7}{100}=0.07$ | $\frac{3}{100}=0.03$ |
| 1 | $\frac{5}{250}=0.02$ | $\frac{205}{250}=0.82$ | $\frac{40}{250}=0.16$ |
| 2 | $\frac{30}{150}=0.20$ | $\frac{18}{150}=0.12$ | $\frac{102}{150}=0.68$ |

## Markov Analysis

- State variable, $X_{n}=$ brand purchased in week $n$
- $\left\{X_{n}\right\}$ represents a discrete state and discrete time stochastic process, where $\boldsymbol{S}=\{1,2,3\}$ and $N=\{0,1,2, \ldots\}$.
- If $\left\{X_{n}\right\}$ has Markovian property and $\mathbf{P}$ is stationary, then a Markov chain should be a reasonable representation of aggregate consumer brand switching behavior.


## Potential Studies

- Predict market shares at specific future points in time.
- Assess rates of change in market shares over time.
- Predict market share equilibriums (if they exist).
- Evaluate the process for introducing new products.


## Transform a Process to a Markov Chain

Sometimes a non-Markovian stochastic process can be transformed into a Markov chain by expanding the state space.

Example: Suppose that the chance of rain tomorrow depends on the weather conditions for the previous two days (yesterday and today).

Specifically, $\operatorname{Pr}\{$ rain tomorrow $\mid$ rain last 2 days (RR) $\} \quad=0.7$
$\operatorname{Pr}\{$ rain tomorrow $\mid$ rain today but not yesterday (NR) $\}=0.5$
$\operatorname{Pr}\{$ rain tomorrow $\mid$ rain yesterday but not today (RN) $\}=0.4$
$\operatorname{Pr}\{$ rain tomorrow $\mid$ no rain in last 2 days (NN) \} $\quad=0.2$
Does the Markovian Property Hold ?

## The Weather Prediction Problem

How to model this problem as a Markov Process ?
The state space: $0=(\mathrm{RR}) 1=(\mathrm{NR}) 2=(\mathrm{RN}) 3=(\mathrm{NN})$
The transition matrix:

|  |  | $0(\mathrm{RR})$ | $1(\mathrm{NR})$ | $2(\mathrm{RN})$ | $3(\mathrm{NN})$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | (RR) | 0.7 | 0 | 0.3 | 0 |
| $\mathbf{P}=$ | $1(\mathrm{NR})$ | 0.5 | 0 | 0.5 | 0 |
| $2(\mathrm{RN})$ | 0 | 0.4 | 0 | 0.6 |  |
| 3 (NN) | 0 | 0.2 | 0 | 0.8 |  |
|  |  |  |  |  |  |

This is a discrete-time Markov process.

## Multi-step ( $n$-step) Transitions

The $\mathbf{P}$ matrix is for one step: $n$ to $n+1$.
How do we calculate the probabilities for transitions involving more than one step?

Consider an IRS auditing example:
Two states: $\mathbf{s}^{0}=0$ (no audit), $\mathbf{s}^{1}=1$ (audit)
Transition matrix $\mathbf{P}=\left[\begin{array}{cc}0.6 & 0.4 \\ 0.5 & 0.5\end{array}\right]$
Interpretation: $p_{01}=0.4$, for example, is conditional probability of an audit next year given no audit this year.

## Two-step Transition Probabilities

Let $p_{i j}^{(2)}$ be probability of going from $i$ to $j$ in two transitions. In matrix form, $\mathbf{P}^{(2)}=\mathbf{P} \times \mathbf{P}$, so for IRS example we have

$$
\mathbf{P}^{(2)}=\left[\begin{array}{ll}
0.6 & 0.4 \\
0.5 & 0.5
\end{array}\right] \times\left[\begin{array}{ll}
0.6 & 0.4 \\
0.5 & 0.5
\end{array}\right]=\left[\begin{array}{ll}
0.56 & 0.44 \\
0.55 & 0.45
\end{array}\right]
$$

The resultant matrix indicates, for example, that the probability of no audit 2 years from now given that the current year there was no audit is $p_{00}^{(2)}=0.56$.

## $n$-Step Transition Probabilities

This idea generalizes to an arbitrary number of steps.
For $n=3: \mathrm{P}^{(3)}=\mathrm{P}^{(2)} \mathrm{P}=\mathrm{P}^{2} \mathrm{P}=\mathrm{P}^{3}$

$$
\text { or more generally, } \mathrm{P}^{(n)}=\mathrm{P}^{(m)} \mathrm{P}^{(n-m)}
$$

The $i j$ th entry of this reduces to

$$
p_{i j}^{(n)}=\sum_{k=0}^{m} p_{i k}^{(m)} p_{k j}^{(n-m)} \quad 1 \leq m \leq n-1
$$

Chapman - Kolmogorov Equations
Interpretation:
RHS is the probability of going from $i$ to $k$ in $m$ steps
\& then going from $k$ to $j$ in the remaining $n-m$ steps, summed over all possible intermediate states $k$.

## n-Step Transition Matrix for IRS Example

| Time, $n$ | Transition matrix, $\mathbf{P}^{(n)}$ |
| :---: | :---: |
| 1 | $\left[\begin{array}{ll}0.6 & 0.4 \\ 0.5 & 0.5\end{array}\right]$ |
| 2 | $\left[\begin{array}{ll}0.56 & 0.44 \\ 0.55 & 0.45\end{array}\right]$ |
| 3 | $\left[\begin{array}{ll}0.556 & 0.444 \\ 0.555 & 0.445\end{array}\right]$ |
| 4 | $\left[\begin{array}{ll}0.5556 & 0.4444 \\ 0.5555 & 0.4445\end{array}\right]$ |
| 5 | $\left[\begin{array}{ll}0.55556 & 0.44444 \\ 0.55555 & 0.44445\end{array}\right]$ |

## Gambler's Ruin Revisited for $p=0.75$

State-transition network


State-transition matrix

|  | 0 | 1 | 2 | 3 | 4 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 1 | 0 | 0 | 0 | 0 |
| 1 | 0.25 | 0 | 0.75 | 0 | 0 |
| 2 | 0 | 0.25 | 0 | 0.75 | 0 |
| 3 | 0 | 0 | 0.25 | 0 | 0.75 |
| 4 | 0 | 0 | 0 | 0 | 1 |

## Gambler's Ruin with $p=0.75, n=30$


( $\varepsilon$ is very small nonunique number)
What does matrix mean?
A steady state probability does not exist.

## DTMC Add-in for Gambler's Ruin



## 30-Step Transition Matrix for Gambler's Ruin



## Limiting probabilities

|  | A | B | C | D | E | F | G | H | I | J | K |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | Absorbing State Ana 2 absorbing state classes <br> Type: DTMC 3 transient states <br> Title:ımbler_Ruin  <br>  Matrix shows long term transition probabilities from transient to absorb |  |  |  |  |  |  |  |  |  |  |
| 2 |  |  |  |  |  |  |  |  |  |  |  |
| 3 |  |  |  |  |  |  |  |  |  |  |  |
| 4 |  |  |  |  |  |  |  |  |  |  |  |
| 5 | Matrix |  |  | Class-1 Class-2 <br> State 0 State 4 |  |  |  |  |  |  |  |
| 6 |  |  |  |  |  |  |  |  |  |
| 7 | Transient St ate 1 |  |  |  |  | $0.325 \quad 0.675$ |  |  |  |  |  |  |  |
| 8 | Transient St ate 2Transient State 3 |  |  | 0.1 | 0.9 |  |  |  |  |  |  |
| 9 |  |  |  | 0.025 | 0.975 |  |  |  |  |  |  |
| 10 | Transient State 3 |  |  |  |  |  |  |  |  |  |  |

## Conditional vs. Unconditional Probabilities

Let state space $\mathbf{S}=\{1,2, \ldots, m\}$.
Let $p_{t j}^{(n)}$ be conditional $n$-step transition probability $\rightarrow \mathrm{P}^{(n)}$.
Let $\mathbf{q}(n)=\left(q_{1}(n), \ldots, q_{m}(n)\right)$ be vector of all unconditional probabilities for all $m$ states after $n$ transitions.

Perform the following calculations:

$$
\mathbf{q}(n)=\mathbf{q}(0) \mathbf{P}^{(n)} \text { or } \mathbf{q}(n)=\mathbf{q}(n-1) \mathbf{P}
$$

where $\mathbf{q}(0)$ is initial unconditional probability.
The components of $\mathbf{q}(n)$ are called the transient probabilities.

## Brand Switching Example $\rightarrow$

We approximate $q_{i}(0)$ by dividing total customers using brand $i$ in week 27 by total sample size of 500:

$$
q(0)=(125 / 500,230 / 500,145 / 500)=(0.25,0.46,0.29)
$$

To predict market shares for, say, week 29 (that is, 2 weeks into the future), we simply apply equation with $n=2$ :

$$
\mathbf{q}(2)=\mathbf{q}(0) \mathbf{P}^{(2)}
$$

$\mathbf{q}(2)=(0.25,0.46,0.29)\left[\begin{array}{lll}0.90 & 0.07 & 0.03 \\ 0.02 & 0.82 & 0.16 \\ 0.20 & 0.12 & 0.68\end{array}\right]^{2}$
$=(0.327,0.406,0.267)$
$=$ expected market share from brands 1, 2, 3

## Transition Probabilities for $n$ Steps

Property 1: Let $\left\{X_{n}: n=0,1, \ldots\right\}$ be a Markov chain with state space $\boldsymbol{S}$ and state-transition matrix $\mathbf{P}$. Then for $i$ and $j \in S$, and $n=1,2, \ldots$

$$
\operatorname{Pr}\left\{X_{n}=j \mid X_{0}=i\right\}=p_{i j}^{(n)}
$$

where the right-hand side represents the $i j^{\text {th }}$ element of the matrix $\mathbf{P}^{(n)}$.

## Steady-State Probabilities

Property 2: Let $\pi=\left(\pi_{1}, \pi_{2}, \ldots, \pi_{m}\right)$ is the $m$-dimensional row vector of steady-state (unconditional) probabilities for the state space $S=\{1, \ldots, m\}$. To find steady-state probabilities, solve linear system:

$$
\boldsymbol{\pi}=\boldsymbol{\pi} \mathbf{P}, \Sigma_{j=1, m} \pi_{j}=1, \pi_{j} \geq 0, j=1, \ldots, m
$$

Brand switching example:
$\left(\pi_{1}, \pi_{2}, \pi_{3}\right)=\left(\pi_{1}, \pi_{2}, \pi_{3}\right)\left[\begin{array}{lll}0.90 & 0.07 & 0.03 \\ 0.02 & 0.82 & 0.16 \\ 0.20 & 0.12 & 0.68\end{array}\right]$

$$
\pi_{1}+\pi_{2}+\pi_{2}=1, \quad \pi_{1} \geq 0, \quad \pi_{2} \geq 0, \quad \pi_{3} \geq 0
$$

## Steady-State Equations for Brand Switching Example

$$
\begin{aligned}
& \pi_{1}=0.90 \pi_{1}+0.02 \pi_{2}+0.20 \pi_{3} \\
& \pi_{2}=0.07 \pi_{1}+0.82 \pi_{2}+0.12 \pi_{3} \\
& \pi_{3}=0.03 \pi_{1}+0.16 \pi_{2}+0.68 \pi_{3} \\
& \pi_{1}+\pi_{2}+\pi_{3}=1 \\
& \pi_{1} \geq 0, \pi_{2} \geq 0, \pi_{3} \geq 0
\end{aligned}
$$

## Total of 4 equations in 3 unknowns

$\rightarrow$ Discard $3^{\text {rd }}$ equation and solve the remaining system to get :

$$
\pi_{1}=0.474, \pi_{2}=0.321, \pi_{3}=0.205
$$

$\Rightarrow$ Recall: $\quad q_{1}(0)=0.25, q_{2}(0)=0.46, q_{3}(0)=0.29$

## Comments on Steady-State Results

1. Steady-state predictions are never achieved in actuality due to a combination of
(i) errors in estimating $\mathbf{P}$
(ii) changes in $\mathbf{P}$ over time
(iii) changes in the nature of dependence relationships among the states.
2. Nevertheless, the use of steady-state values is an important diagnostic tool for the decision maker.
3. Steady-state probabilities might not exist unless the Markov chain is ergodic.

## Existence of Steady-State Probabilities

A Markov chain is ergodic if it is aperiodic and allows the attainment of any future state from any initial state after one or more transitions. If these conditions hold, then

$$
\pi_{j}=\lim _{n \rightarrow \infty} p_{i j}^{(n)}
$$

For example,
State-transition network
$\mathbf{P}=\left[\begin{array}{ccc}0.8 & 0 & 0.2 \\ 0.4 & 0.3 & 0.3 \\ 0 & 0.9 & 0.1\end{array}\right]$

Conclusion: chain is ergodic.

$\leqslant$ Craps

## Game of Craps

The game of craps is played as follows. The player rolls a pair of dice and sums the numbers showing.

- Total of 7 or 11 on the first rolls wins for the player
- Total of 2, 3, 12 loses
- Any other number is called the point.

The player rolls the dice again.

- If she rolls the point number, she wins
- If she rolls number 7, she loses
- Any other number requires another roll

The game continues until he/she wins or loses

## Game of Craps as a Markov Chain

All the possible states


Continue

## Game of Craps Network



## Game of Craps

| Sum | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Prob. | 0.028 | 0.056 | 0.083 | 0.111 | 0.139 | 0.167 | 0.139 | 0.111 | 0.083 | 0.056 | 0.028 |

Probability of win $=\operatorname{Pr}\{7$ or 11$\}=0.167+0.056=0.223$
Probability of loss $=\operatorname{Pr}\{2,3,12\}=0.028+0.056+0.028=0.112$

|  |  | ta | Win | Lose | P4 | P5 | P6 | P8 | P9 | P10 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Start | 0 | 0.222 | 0.111 | 0.083 | 0.111 | 0.139 | 0.139 | 0.111 | 0.083 |
|  | Win | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
|  | Lose | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 |
|  | P4 | 0 | 0.083 | 0.167 | 0.75 | 0 | 0 | 0 | 0 | 0 |
| $\mathbf{P}=$ | P5 | 0 | 0.111 | 0.167 | 0 | 0.722 | 0 | 0 | 0 | 0 |
|  | P6 | 0 | 0.139 | 0.167 | 0 | 0 | 0.694 | 0 | 0 | 0 |
|  | P8 | 0 | 0.139 | 0.167 | 0 | 0 | 0 | 0.694 | 0 | 0 |
|  | P9 | 0 | 0.111 | 0.167 | 0 | 0 | 0 | 0 | 0.722 | 0 |
|  | P10 | 0 | 0.083 | 0.167 | 0 | 0 | 0 | 0 | 0 | 0.75 |

## Transient Probabilities for Craps

| Roll, $n$ | $\mathbf{q}(n)$ | Start | Win | Lose | P4 | P5 | P6 | P8 | P9 | P10 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | $\mathbf{q}(0)$ | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 1 | $\mathbf{q}(1)$ | 0 | 0.222 | 0.111 | 0.083 | 0.111 | 0.139 | 0.139 | 0.111 | 0.083 |
| 2 | $\mathbf{q}(2)$ | 0 | 0.299 | 0.222 | 0.063 | 0.08 | 0.096 | 0.096 | 0.080 | 0.063 |
| 3 | $\mathbf{q ( 3 )}$ | 0 | 0.354 | 0.302 | 0.047 | 0.058 | 0.067 | 0.067 | 0.058 | 0.047 |
| 4 | $\mathbf{q}(4)$ | 0 | 0.394 | 0.359 | 0.035 | 0.042 | 0.047 | 0.047 | 0.042 | 0.035 |
| 5 | $\mathbf{q}(5)$ | 0 | 0.422 | 0.400 | 0.026 | 0.030 | 0.032 | 0.032 | 0.030 | 0.026 |

This is not an ergodic Markov chain so where you start is important.

## Absorbing State Probabilities for Craps

| Initial state | Win | Lose |
| :---: | :---: | :---: |
| Start | 0.493 | 0.507 |
| P4 | 0.333 | 0.667 |
| P5 | 0.400 | 0.600 |
| P6 | 0.455 | 0.545 |
| P8 | 0.455 | 0.545 |
| P9 | 0.400 | 0.600 |
| P10 | 0.333 | 0.667 |

## Interpretation of Steady-State Conditions

1. Just because an ergodic system has steady-state probabilities does not mean that the system "settles down" into any one state.
2. The limiting probability $\pi_{j}$ is simply the likelihood of finding the system in state $j$ after a large number of steps.
3. The probability that the process is in state $j$ after a large number of steps is also equals the long-run proportion of time that the process will be in state $j$.
4. When the Markov chain is finite, irreducible and periodic, we still have the result that the $\square_{j}, j \in \mathbf{S}$, uniquely solve the steady-state equations, but now $\Pi_{j}$ must be interpreted as the long-run proportion of time that the chain is in state $j$.

## What You Should Know About Markov Chains

- How to define states of a discrete time process.
- How to construct a state-transition matrix.
- How to find the $n$-step state-transition probabilities (using the Excel add-in).
- How to determine the unconditional probabilities after $n$ steps
- How to determine steady-state probabilities (using the Excel add-in).

